

# **Instrumentation and applications of liquid-environment FM-AFM (Part I)**

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# Outline

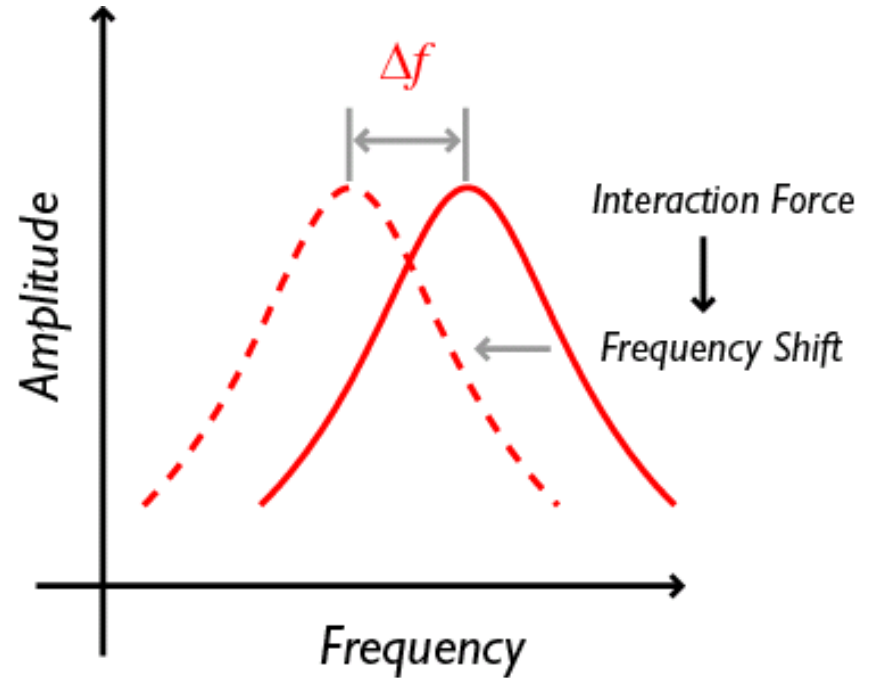
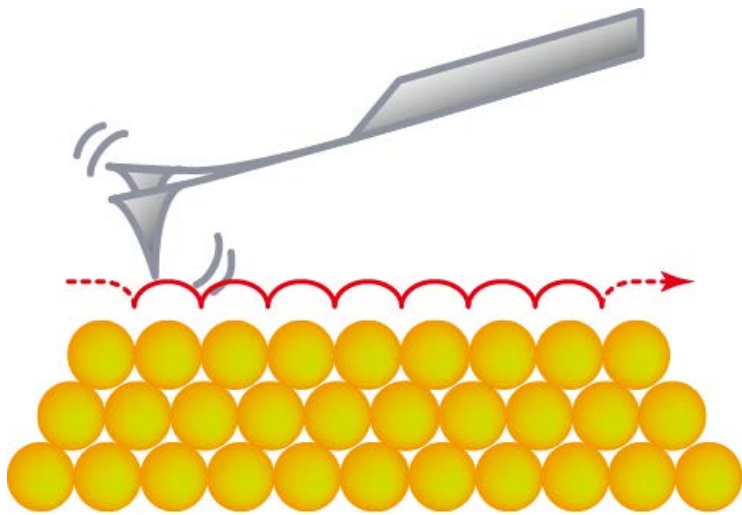
- 1. FM-AFM in Liquid**
- 2. Force Sensitivity**
- 3. Imaging Speed**
- 4. Stability & Reproducibility**
- 5. Summary**

# Outline

- 1. FM-AFM in Liquid**
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# Frequency Modulation AFM (FM-AFM)

## Principle

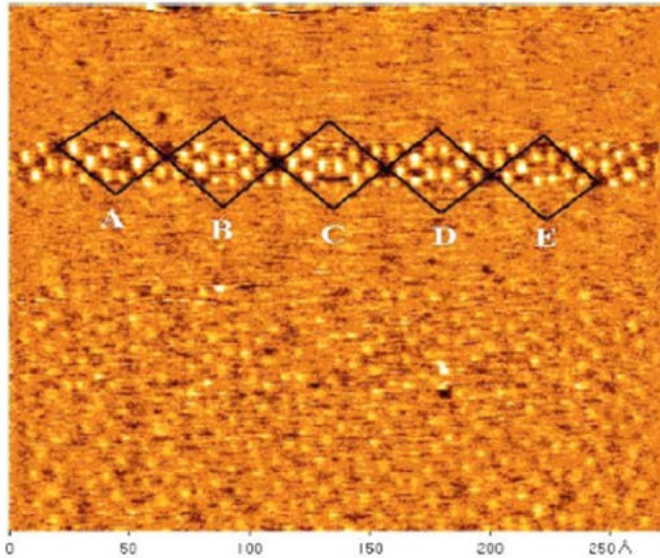


- True atomic resolution
- Conductive & Non-conductive surfaces
- Small loading force

# True Atomic-resolution FM-AFM Imaging

## In Vacuum

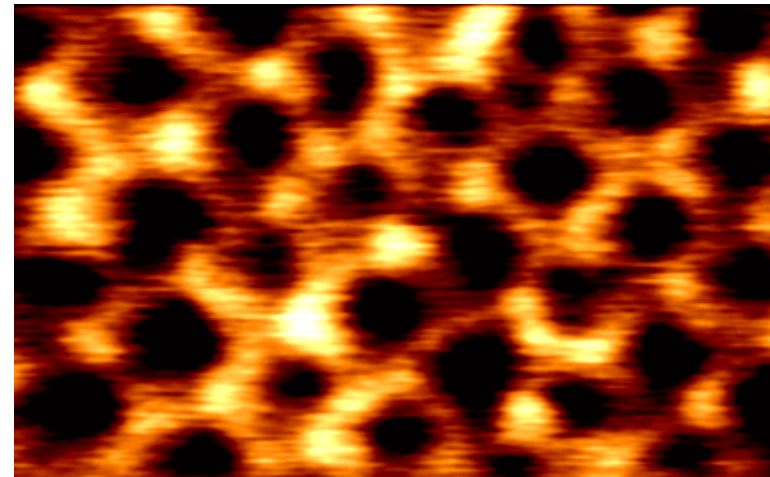
### Si(111) in Vacuum



F. J. Giessibl, *Science* 267 (1995) 68

## In Liquid

### Mica in Water



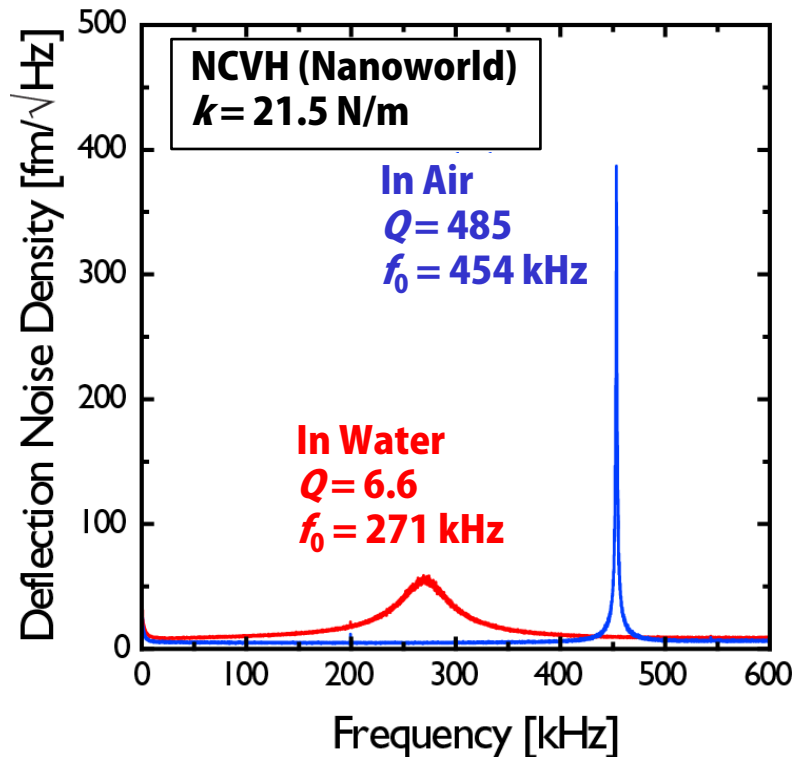
Fukuma *et al.* *APL* 87 (2005) 034101

**Operating environment of FM-AFM  
was limited to vacuum for 10 years**

# Difficulties in Liquid

## Hydrodynamic Damping

### Cantilever Thermal Vibration



### Low Q Factor

Vacuum	1,000 – 100,000
Air	100 – 1,000
Liquid	1 – 10

### Minimum Detectable Force

$$F_{\min} = \sqrt{\frac{4kk_BTB}{\pi f_0 Q}}$$

$F_{\min}$  was considered to be limited **mainly** by cantilever

# Major Improvements

## Stiff Cantilevers

### Thermal Vibration

$$z_{\text{th}} = \sqrt{\frac{k_B T}{k}}$$

### Conventional

$k = 0.4 \text{ N/m}$   
 $z_{\text{th}} = 100 \text{ pm}$



### Improved

$k = 40 \text{ N/m}$   
 $z_{\text{th}} = 10 \text{ pm}$

## Small Oscillation Amplitude

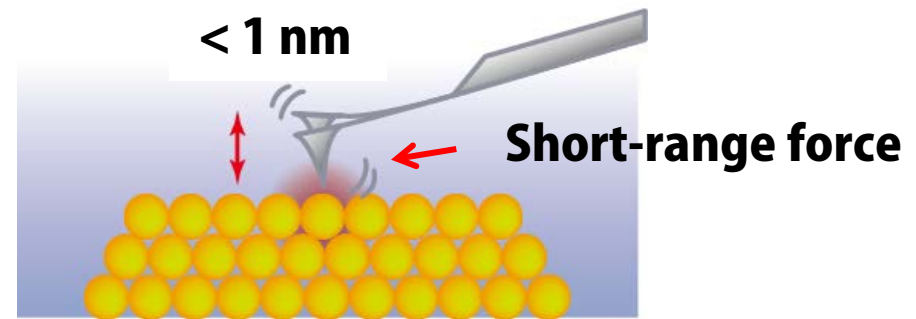
### Conventional

$A = 1-10 \text{ nm}$

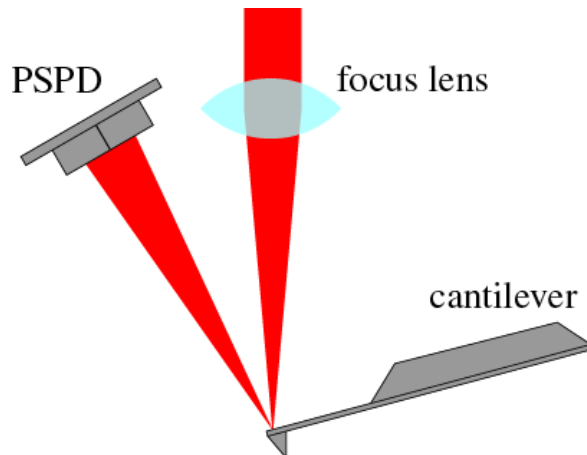


### Improved

$A = 0.1-1 \text{ nm}$



## Low-noise Cantilever Deflection Sensor



### Conventional

$n = 100-1,000 \text{ fm}/\sqrt{\text{Hz}}$



### Improved

$n = 40 \text{ fm}/\sqrt{\text{Hz}}$  (2005)

$n = 7.3 \text{ fm}/\sqrt{\text{Hz}}$  (2006)

$n = 4.7 \text{ fm}/\sqrt{\text{Hz}}$  (2009)

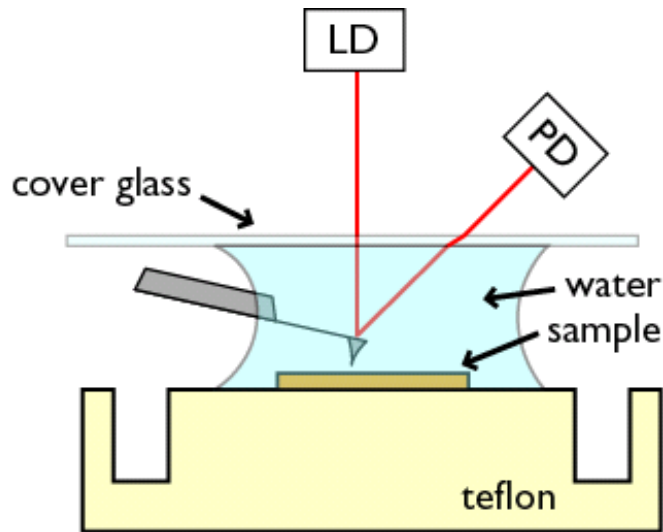
Fukuma *et al.* RSI 76 (2005) 053704

Fukuma *et al.* RSI 77 (2006) 043701

Fukuma RSI 80 (2009) 023707

# Reduction of Deflection Sensor Noise

## Noise from Laser



**Interfaces in the optical path**



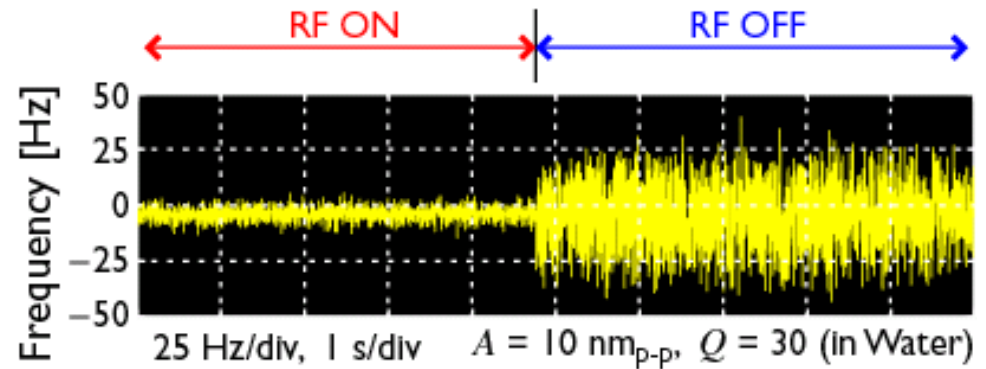
**Reflection, Scattering**



- **Optical feedback noise**
- **Interference noise**

## RF Modulation of Laser

### Frequency Shift



**RF modulation of laser at 300 MHz**



**Suppression of coherence**



**Reduction of noise**

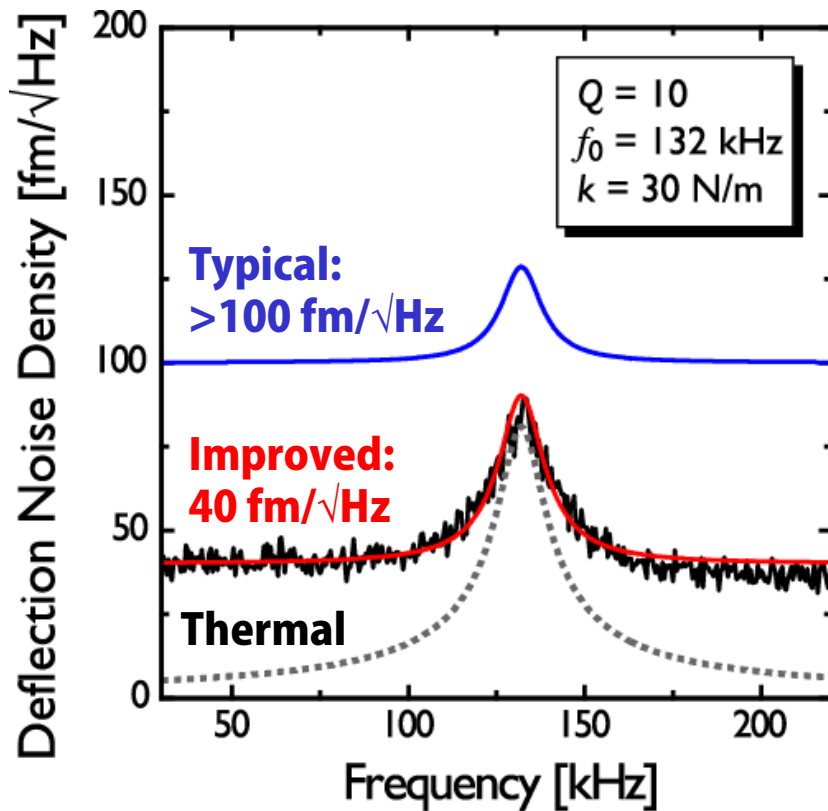
- **Mode hop noise**
- **Interference noise**



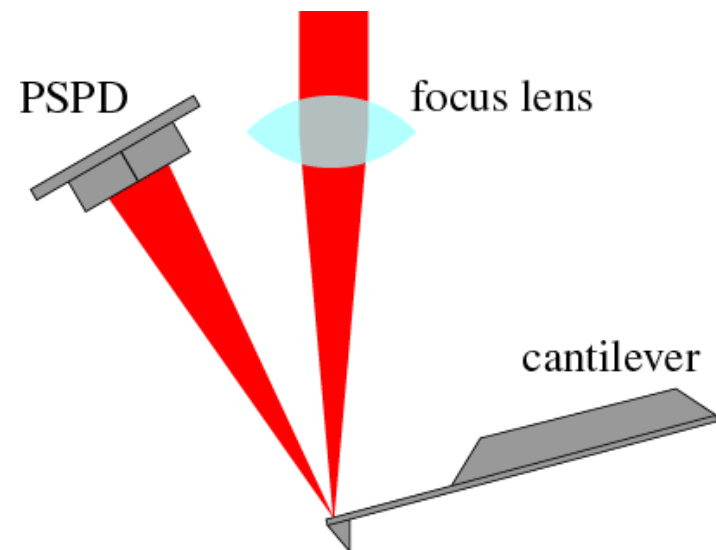
# Atomic-resolution FM-AFM in Liquid

Thermal-noise-limited  $F_{\min}$

FFT Spectrum of Deflection Signal



Low Noise Deflection Sensor



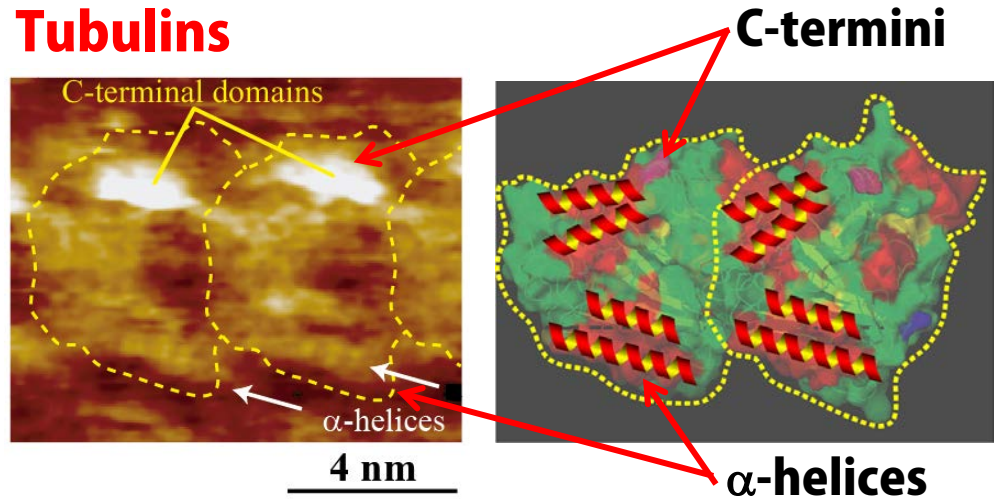
Fukuma *et al.* RSI 76 (2005) 053704

- Thermal-noise-limited  $F_{\min} \rightarrow$  True atomic resolution
- Now,  $F_{\min}$  is indeed limited mainly by cantilever

# Liquid-environment FM-AFM

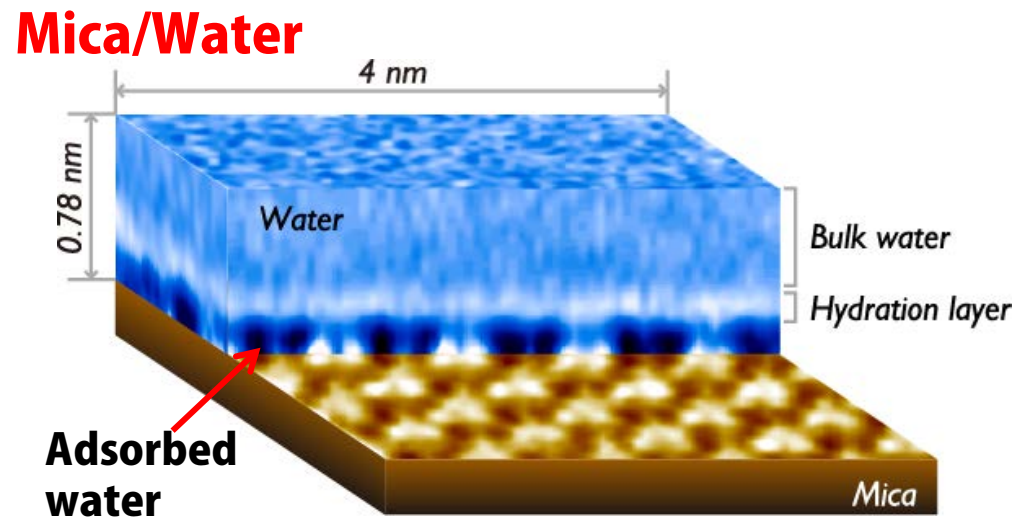
## Biological Systems

- Hoogenboom et al. APL 88 (2006) 193109
- Higgins et al. BPJ 91 (2006) 2532
- Fukuma et al. PRL 98(2007) 106101
- Yamada et al. APEX 2 (2009) 095007
- Nagashima et al. JVSTB 28 (2010) C4C11
- Asakawa *et al.* BPJ 110 (2011) 1270



## 3D Hydration Structures

- Fukuma *et al.* PRL 104 (2010) 016101
- Kimura *et al.* JCP 132 (2010) 194705
- K. Suzuki *et al.* APEX 4 (2011) 125102
- H. Asakawa *et al.* ACS NANO 6 (2012) 9013
- T. Hiasa *et al.* PCCP 14 (2012) 8419



- Application techniques significantly advanced
- $F_{\min}$  is still limited by cantilever

# Outline

**1. FM-AFM in Liquid**

**2. Force Sensitivity**

**3. Imaging Speed**

**4. Stability & Reproducibility**

**5. Summary**

# Theoretical Limit of FM-AFM

## Minimum Detectable Force

**Small Amplitude Approx.**

$$F_{\min} = \sqrt{\frac{4kk_B T B}{\pi f_0 Q}}$$

**$k$ : Spring constant**  
 **$Q$ : Q factor**  
 **$f_0$ : Resonance Freq.**

## Influence of Fluids

**Typical Values (NCH)**

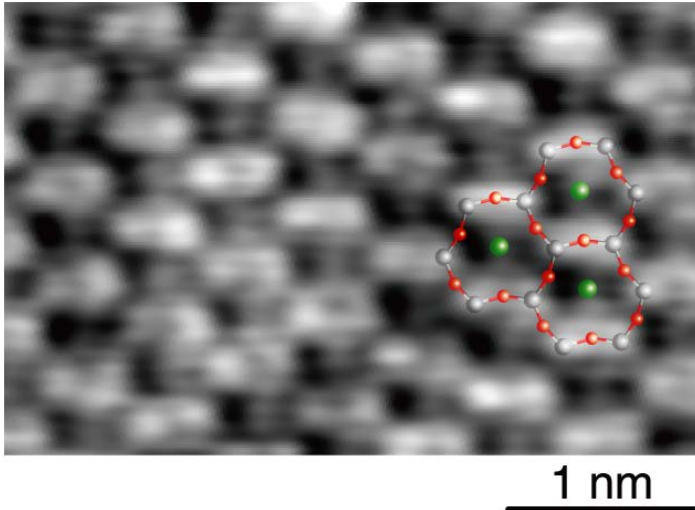
	Vacuum	Liquid
$Q$	30,000	8
$f_0$	300 kHz	130 kHz
$F_{\min}$ ( $B$ :100 Hz)	0.04 pN	<b>4 pN</b>

- $F_{\min}$  is determined by cantilever parameters
- $F_{\min}$  in liquid is much worse than that in vacuum

# Required Force Resolution

## Atomic-resolution Image

### Mica in Liquid



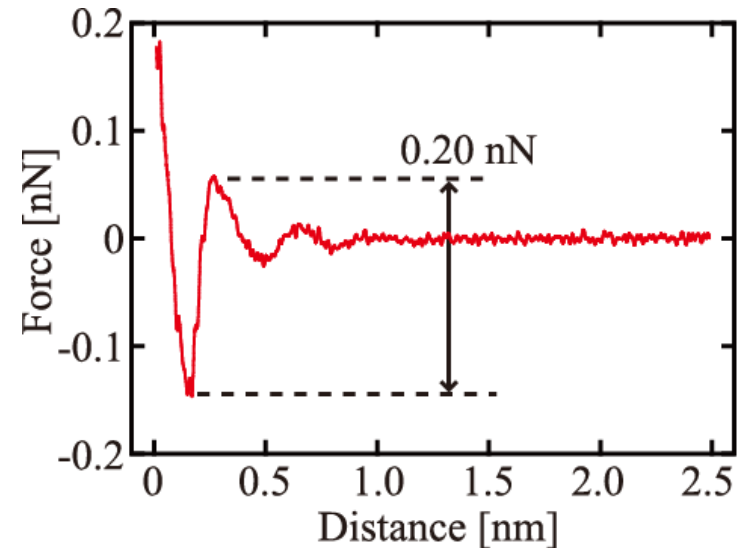
**Corrugation : 10 - 100 pm**

**Force gradient : 0.3 - 3 N/m**

**→  $F_{\min}$  : 3 - 300 pN**

## Hydration Force

### Mica/Water Interface



**Hydration force : 3- 300 pN**

**→  $F_{\min}$  : 3 - 300 pN**

**Present AFM barely satisfies these requirements**

**→ Low reproducibility, reliability**

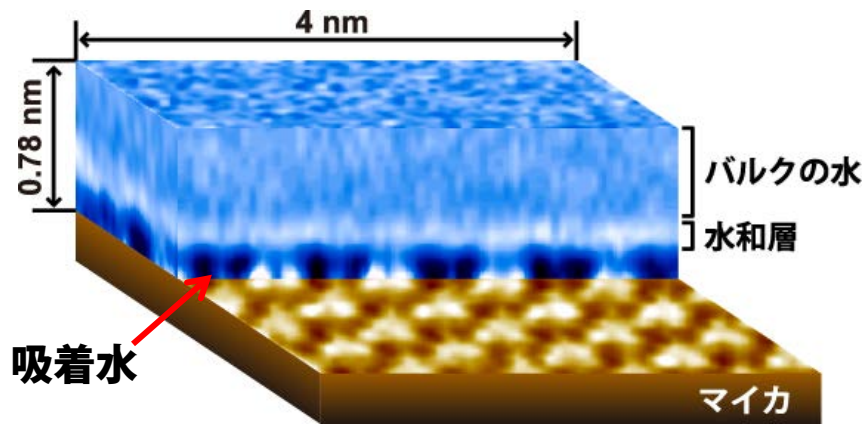
**→ Dependent on skills, samples, solution**

# Required Force Resolution

## 3D Hydration Structure

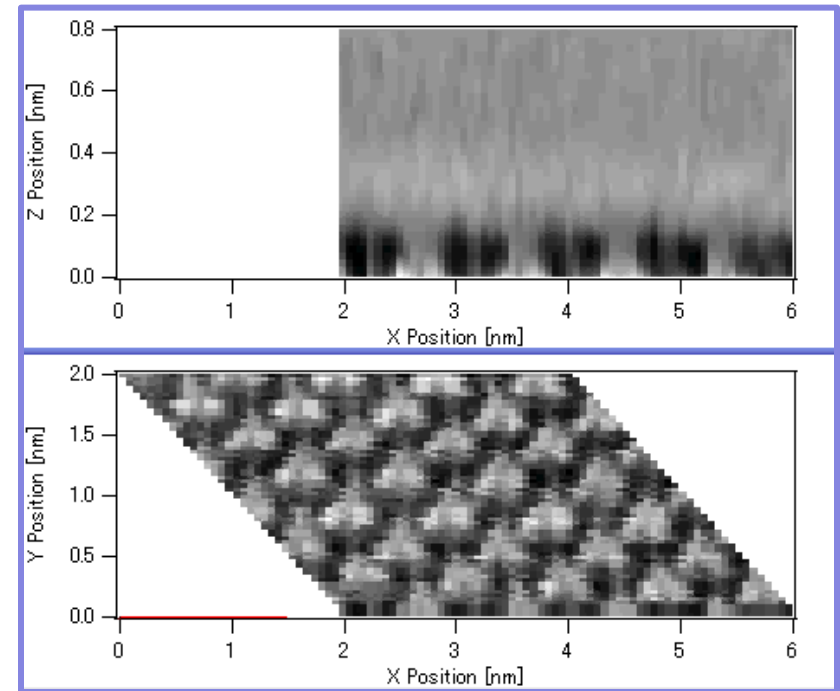
Fukuma *et al.* PRL 104 (2010) 016101

### Mica/Water Interface



- XZ Image: 0.82 sec/frame
- 3D Image: 53 sec/frame

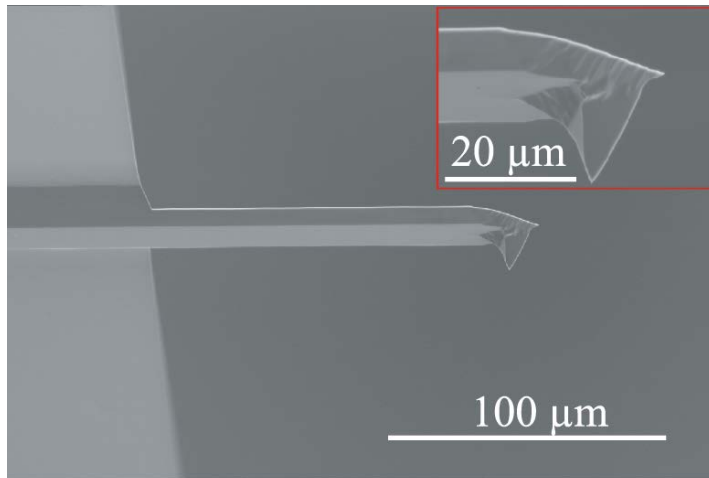
### XY & Z Cross Sections



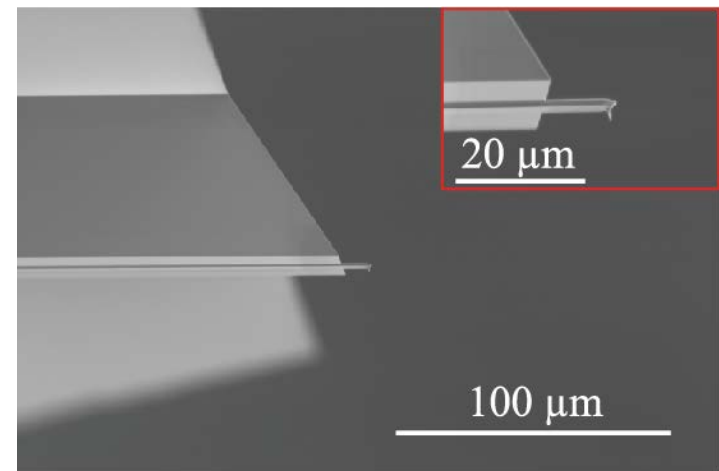
- 3D force measurement requires  $B > 1$  kHz
- $F_{\min}$  of present AFM is not necessarily sufficient

# Small Cantilevers (Nanoworld)

## Conventional (NCH)



## Small (USC - Prototype)



	$\ell$ [μm]	$t$ [μm]	$w$ [μm]	$k$ [N/m]	$Q$	$f_0$ [kHz]	$F_{\min} @ B = 100 \text{ Hz}$ [pN]
<b>Conventional</b>	<b>136</b>	<b>3.7</b>	<b>30</b>	<b>26</b>	<b>6</b>	<b>130</b>	<b>4.2</b>
<b>Small</b>	<b>11</b>	<b>0.8</b>	<b>4.8</b>	<b>29</b>	<b>5</b>	<b>2800</b>	<b>1.0</b>

# Deflection Sensor

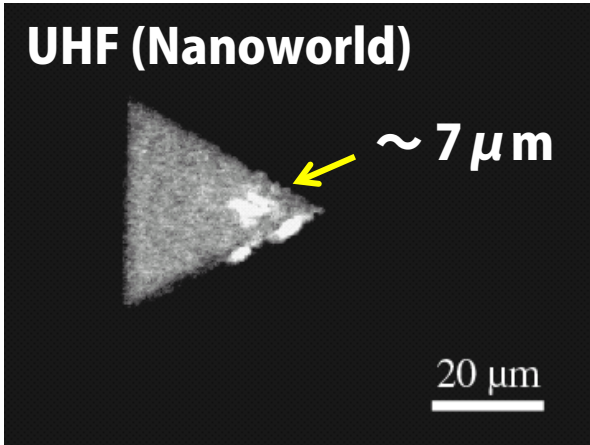
## Special Requirements

### Wideband

Bandwidth:  $\sim 10$  MHz

### High-Mag. Optics

UHF (Nanoworld)

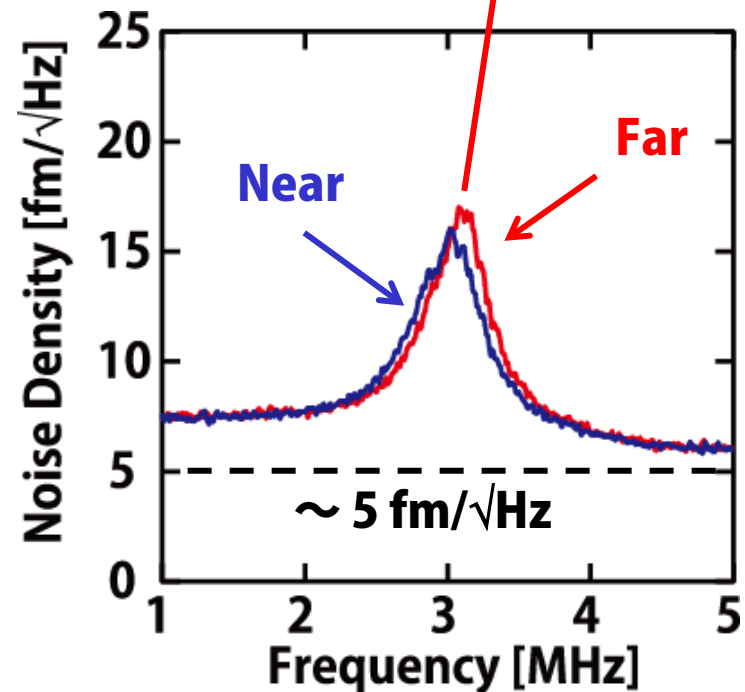


Fukuma et al. RSI 77 (2006) 043701

Fukuma RSI 80 (2009) 023707

### Low Noise

Thermal noise spectrum (USC in water)



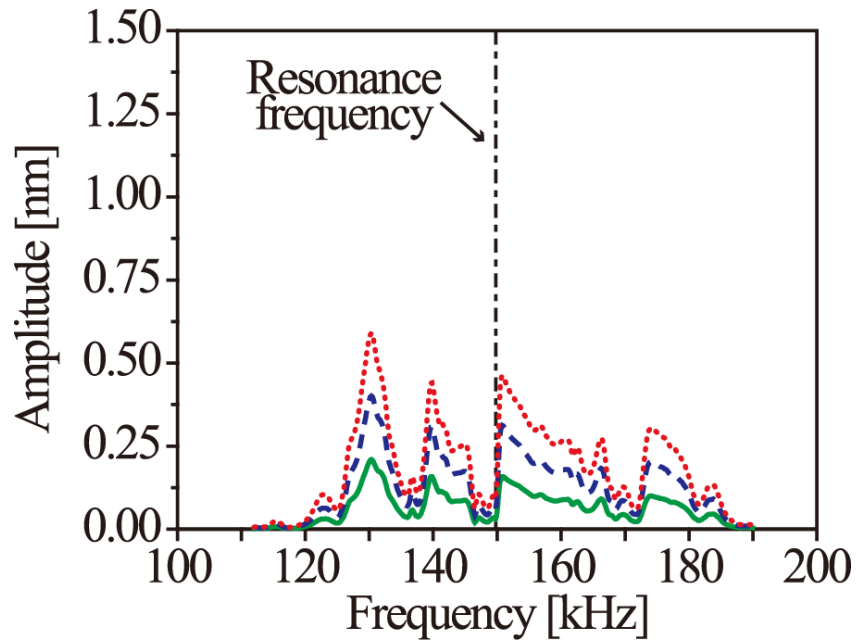
$$n_{zB}(f_0) = \sqrt{\frac{2k_B T Q}{\pi k f_0}}$$

- Clear thermal vibration peak
- Sensor noise is negligible



# Cantilever Excitation

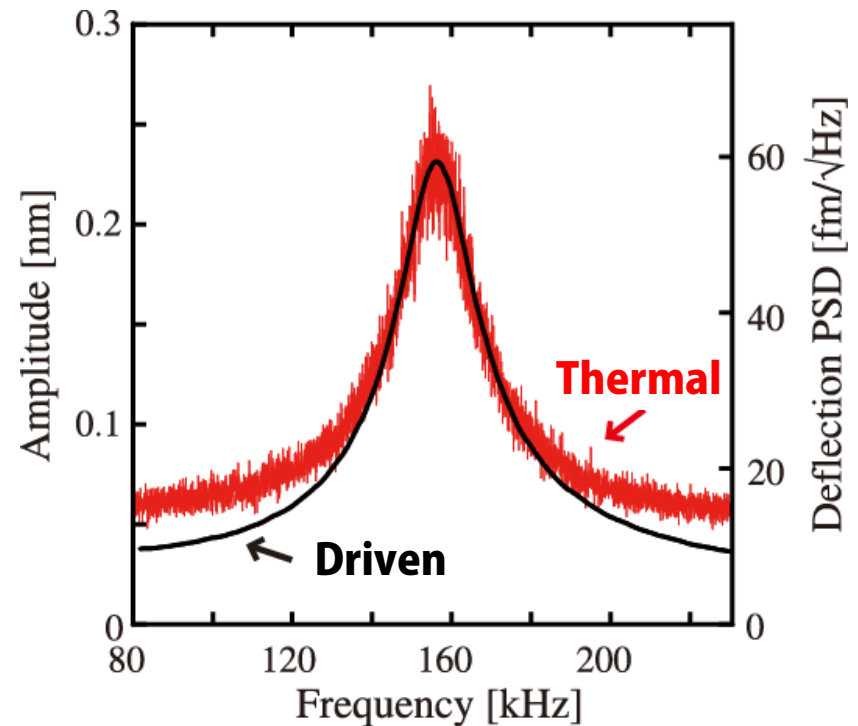
## Piezoelectric Excitation



Asakawa et al. RSI 80 (2009) 103703

- Forest of peaks
- Narrow bandwidth:  $< 1$  MHz

## Photothermal Excitation



Fukuma RSI 80 (2009) 023707

- Ideal cantilever response
- Wide bandwidth:  $> 10$  MHz

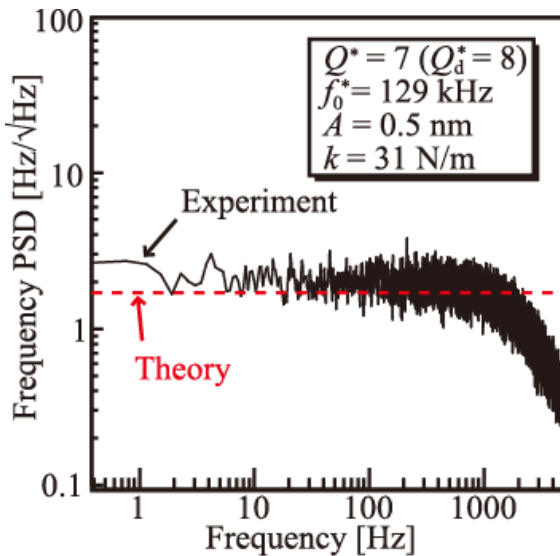
# Instability of Excitation

FM Noise

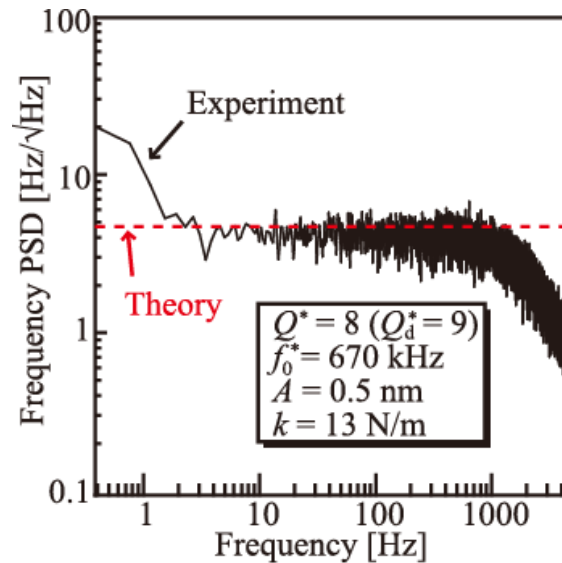
Cantilever Size

Large  $\longleftrightarrow$  Small

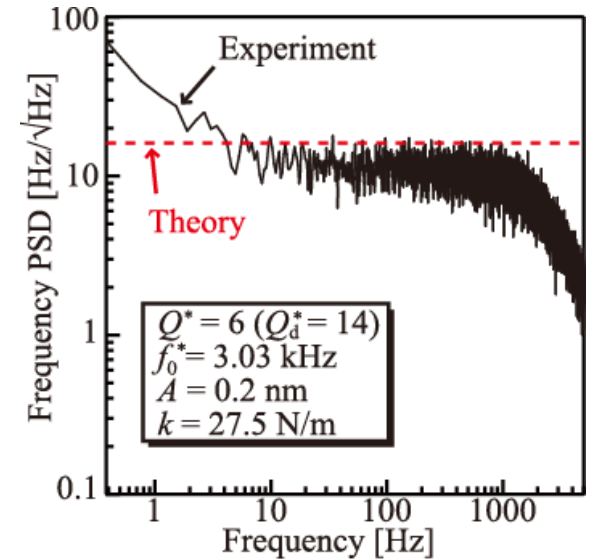
NCH



UHF



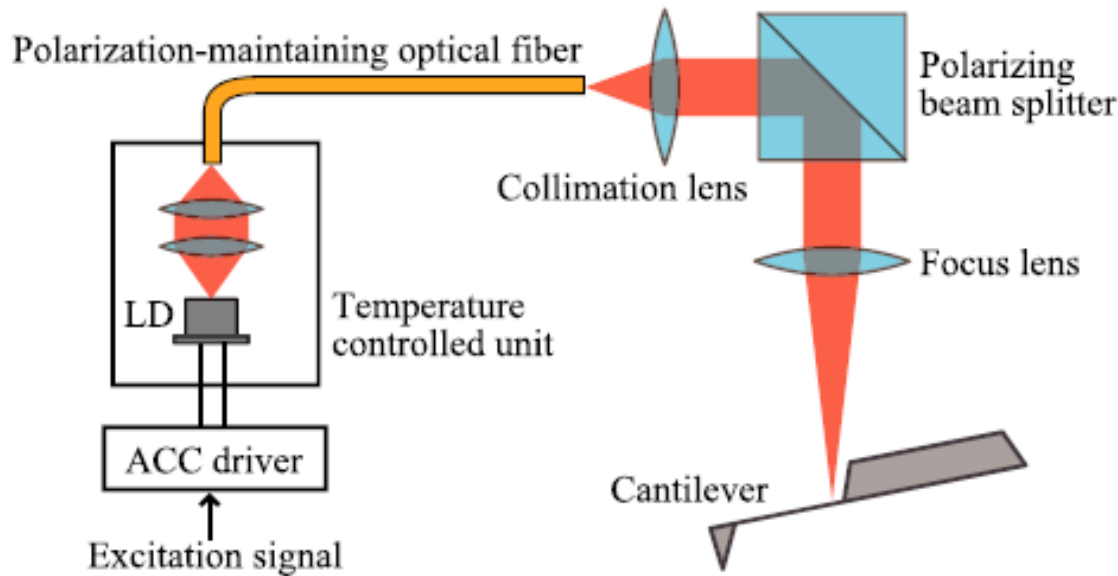
USC



Smaller cantilever shows larger Instability

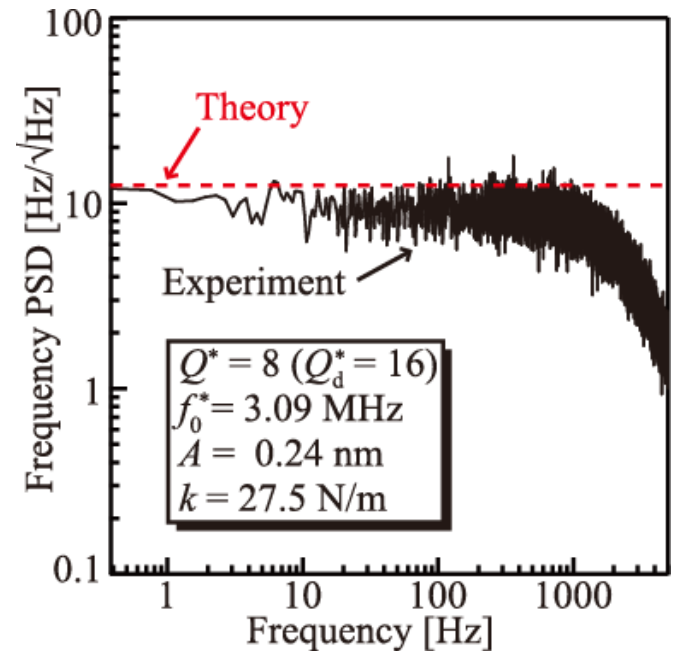
# Improvement in Stability

## Improved Photothermal Excitation Setup



- **APC** → **ACC + TEC**
- **LD+Lens** → **LD + PMF + Lens**

## FM Noise (USC)

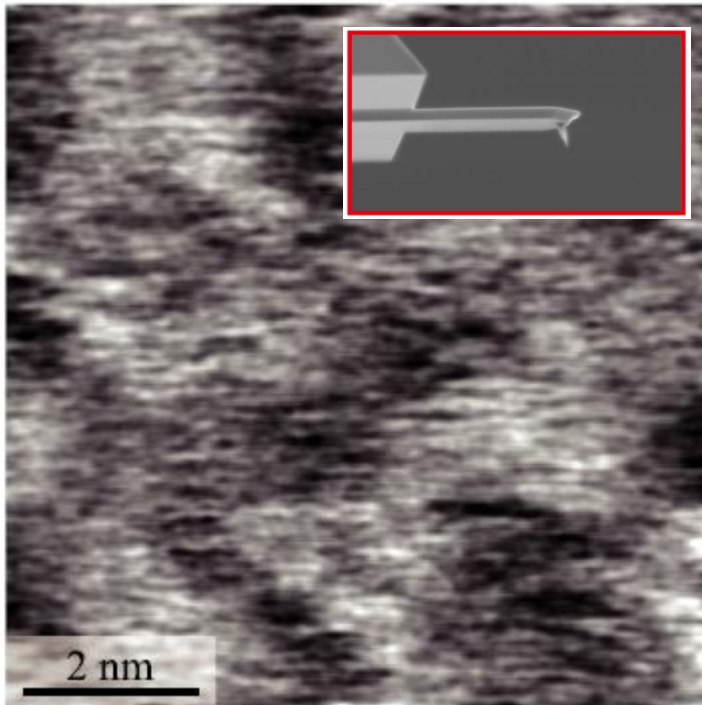


- **ACC + TEC + PMF → Sufficient stability**
- **Theoretically-limited performance with USC**

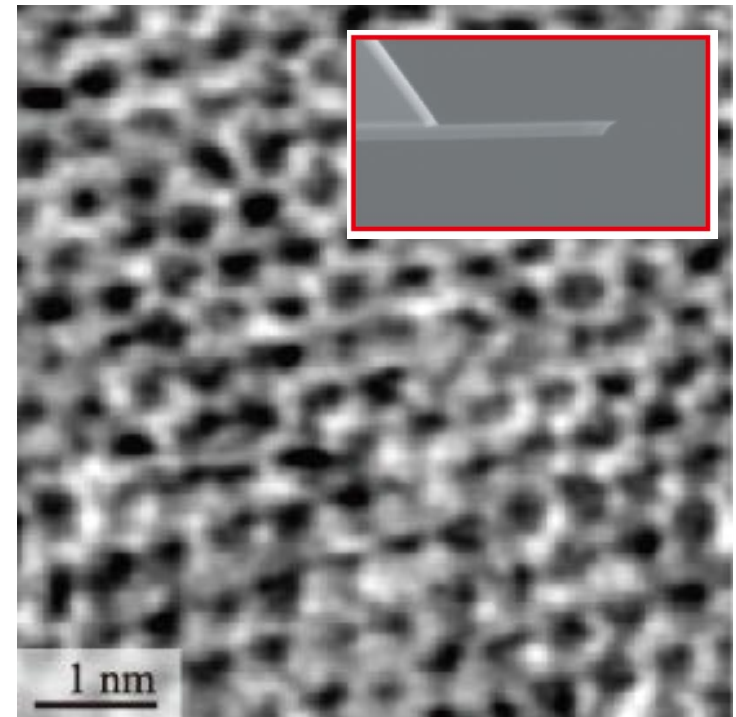
# Problem in Atomic-scale Imaging

## Mica in PBS Solution

USC with EBD tip



USC without Tip

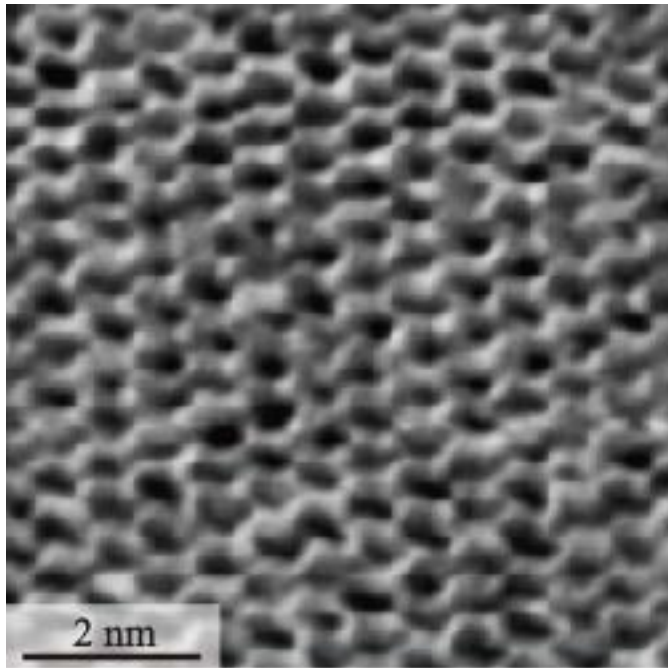


- EBD tip prevents atomic-resolution imaging
- Contamination is one of the reasons

# Surface Treatment of Tip Apex

## Mica in PBS Solution

**USC with Si Coat (30 nm, Tip Side)**



- **High reproducibility**
- **High stability**

- **The tip problem was solved by Si coating**
- **Atomic-resolution imaging by small cantilever !**

# Force Measurements on Mica in Water

**Conventional**

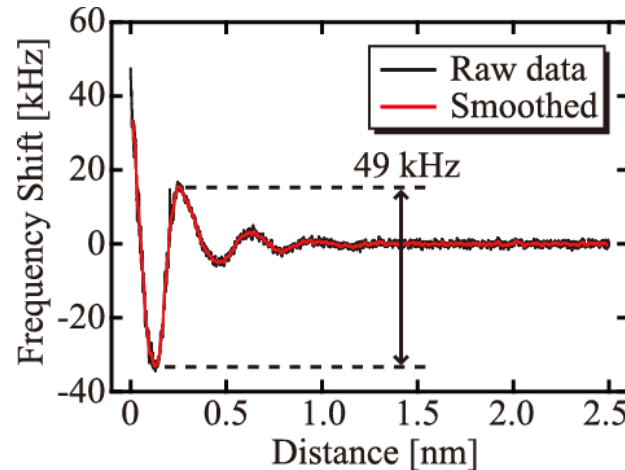
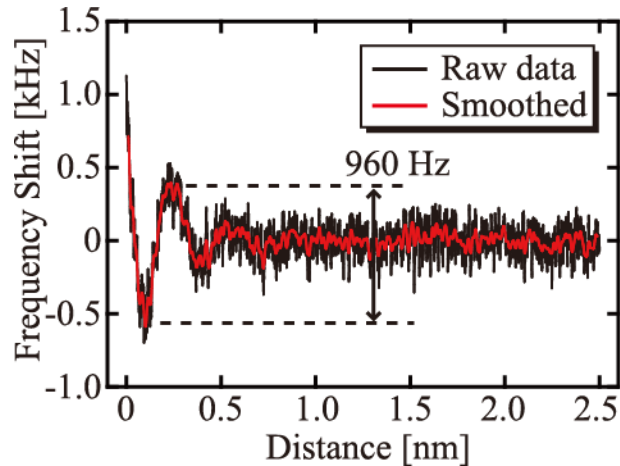
**Small**

Fukuma *et al.* Nanotechnol.  
23 (2012) 135706

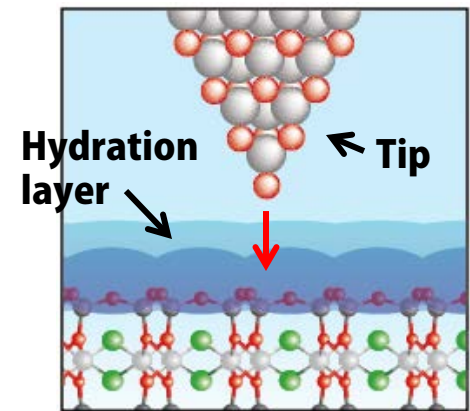
Sens.: 5.7 THz/N

X 43

Sens. : 245 THz/N

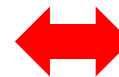


**Mica/water interface**



**7.4 times improvement in  $F_{\min}$**

- 11  $\rightarrow$  1.4 pN @  $B = 100$  Hz
- 34  $\rightarrow$  4.6 pN @  $B = 1$  kHz



**Required  $F_{\min}$**

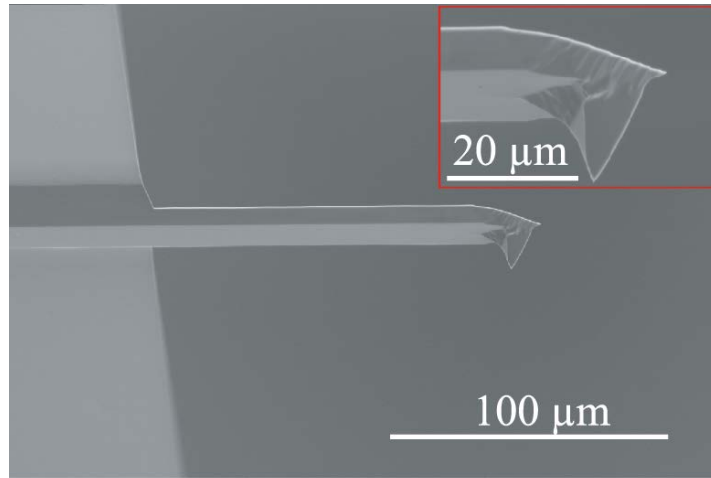
- 2D :  $\sim 10$  pN @ 100 Hz
- 3D :  $\sim 10$  pN @ 1 kHz

# Outline

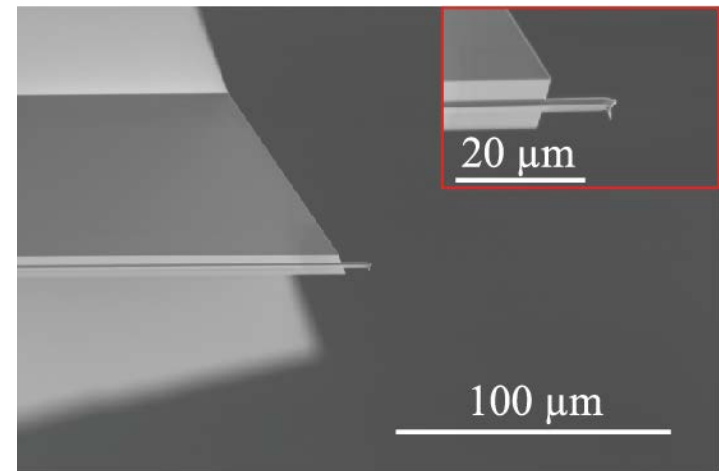
1. FM-AFM in Liquid
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# Another Benefit of Small Cantilever

## Conventional (NCH)



## Small (USC)



	$F_{\min} @ B = 100 \text{ Hz}$	$B @ F_{\min} = 10 \text{ pN}$	Imaging time
Conventional	11 pN	87 Hz	~60 s
Small	1.4 pN	4.8 kHz	~1.1 s
Ratio	×7.4	×55	×1/55

Small Cantilever :  $B = 5 \text{ kHz}$  @  $F_{\min} = 10 \text{ pN}$   
→ Atomic-resolution imaging at **1 s/frame**

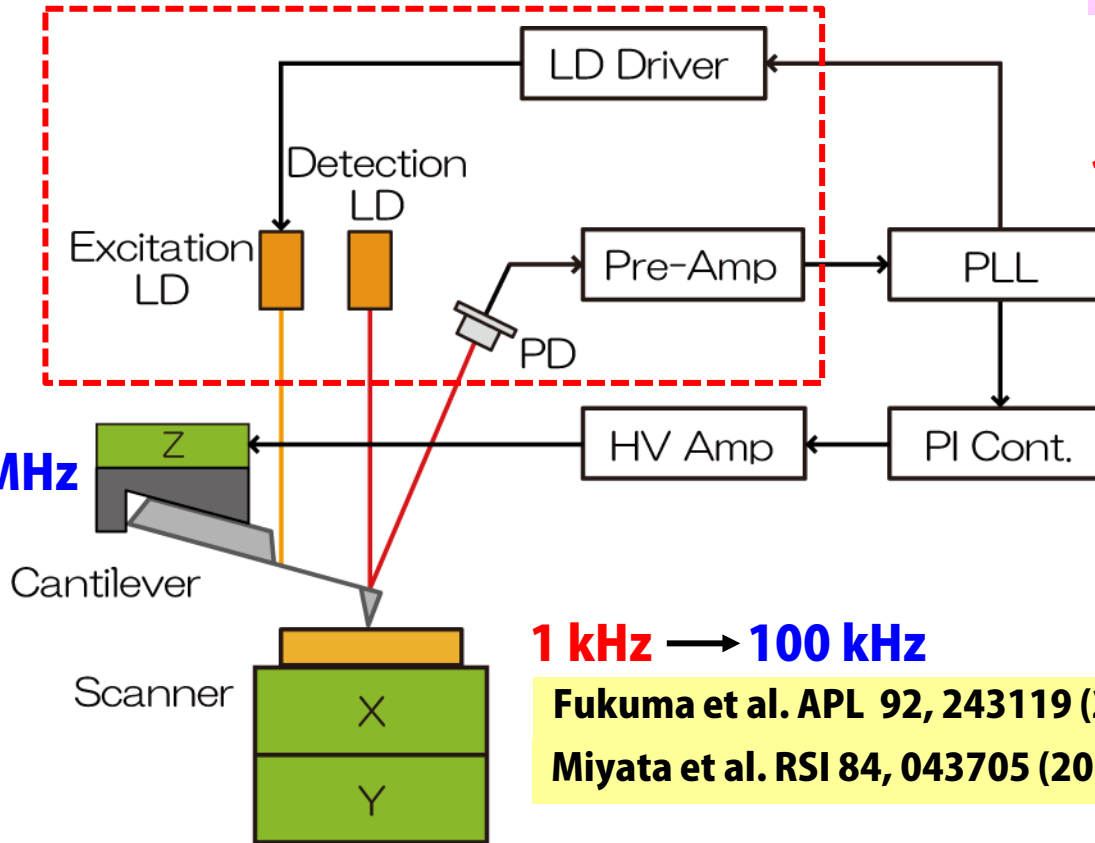


# Improvement of $B$

1 MHz → 10 MHz

Fukuma et al. RSI  
80, 023707 (2009)

Before / After



1 kHz → 100 kHz

Mitani et al. RSI  
80, 083705 (2009)

Miyata et al. APL  
103, 203104 (2013)

150 kHz → 3.5 MHz

Fukuma et al.  
Nanotechnol. 23  
(2012) 135706

1 kHz → 100 kHz

Fukuma et al. APL 92, 243119 (2008)  
Miyata et al. RSI 84, 043705 (2013)

Improvements of individual components

# Outline

1. **FM-AFM in Liquid**
2. **Force Sensitivity**
3. **Imaging Speed**
4. **Stability & Reproducibility**
5. **Summary**

# Summary

## FM-AFM in Liquid

- Stiff cantilever ( $k > 10$  N/m)
- Small amplitude ( $A < 0.5$  nm)
- Low-noise deflection sensor ( $n < 40$  fm/ $\sqrt{\text{Hz}}$ )

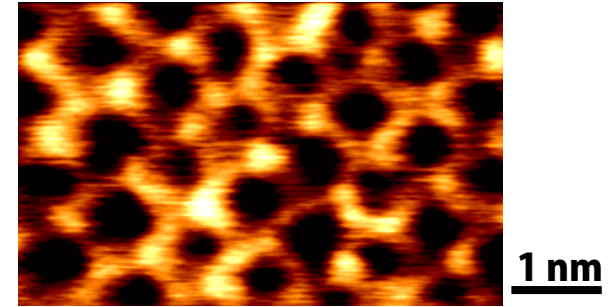
## Force Sensitivity

- Small cantilever ( $L < 10$   $\mu\text{m}$ )
- High resonance frequency ( $f_0 > 3.5$  MHz)
- Low noise deflection sensor ( $n < 10$  fm/ $\sqrt{\text{Hz}}$ )
- Stable photothermal excitation

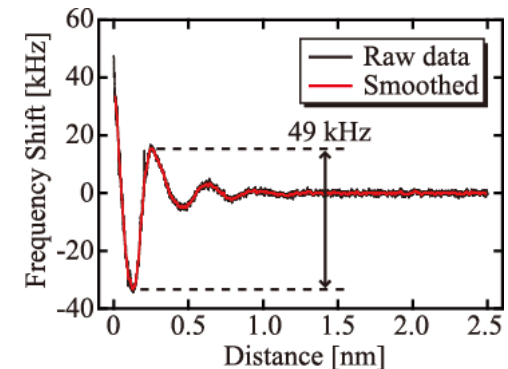
## Imaging Speed

- Small cantilever ( $f_0 > 3.5$  MHz)
- High resonance freq. scanner ( $f_0 > 100$  kHz)
- Wideband & Low-latency PLL ( $\tau < 1.4$   $\mu\text{s}$ )

## Atomic-resolution Imaging



## ~1 pN Force Resolution

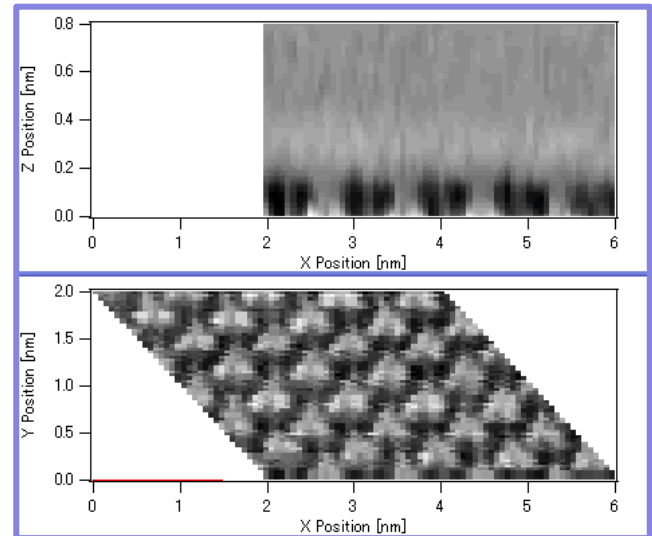


# Summary

## Future Prospects

- **High-speed 3D Imaging**
  - > Time-resolved measurements
- **Single-molecular-level tip modifications**
  - > 3D mapping of molecular interactions
- **Surface property measurements**
  - > Surface potential & charge

## High-speed 3D Imaging



# Acknowledgements

## Collaborators

### **Kanazawa Univ.**

**Hitoshi Asakawa  
Kazuki Miyata  
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Peter Spijker**

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Kei Kobayashi**

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